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Dissipation-assisted Matrix Product Factorization

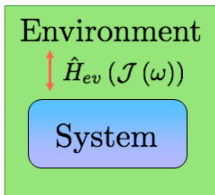
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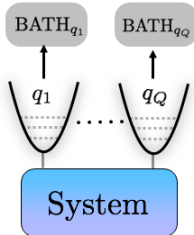
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TENSOR NETWORKS + PSEUDOMODES THEORY

Continuous environmental spectrum



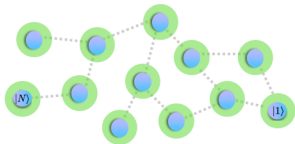
Discrete environment



\equiv

$$C(t) = \int_0^\infty d\omega \mathcal{J}(\omega) \left(\coth\left(\frac{\beta\omega}{2}\right) \cos(\omega t) - i \sin(\omega t) \right)$$

$$C'(t) = \sum_{q,\pm}^{q=Q} \left[\frac{\omega_q^2 s_q}{2} \left(\coth\left(\frac{\beta_q \omega_q}{2}\right) \pm 1 \right) e^{\mp i\omega_q t - \gamma_q t} \right]$$



$$\hat{\rho} = \sum_{m,n=1}^N \overset{\text{electronic states}}{|m\rangle\langle n|} \otimes \hat{\mathcal{O}}_{m,n}$$



$$\hat{\mathcal{O}}_{m,n} = \sum_{j_1, \dots, j_M=1}^{N_b^2} A_{1,j_1}^{(m,n)} A_{2,j_2}^{(m,n)} \dots A_{M,j_M}^{(m,n)} \hat{x}_{j_1} \otimes \dots \otimes \hat{x}_{j_M}$$

- electronic states
- vibrational environment

TENSOR NETWORKS + PSEUDOMODES THEORY = DAMPF

- ▶ Numerically exact
- ▶ Capable of describing highly structured environments
- ▶ Capable of computing environmental quantities
- ▶ Highly parallelizable
- ▶ Polynomial scaling with system's dimensions
- ▶ Memory efficient
- ▶ Error control

Model:

$$\hat{H}_S = \hat{H}_e + \hat{H}_v + \hat{H}_{ev}$$

$$\hat{H}_e = \sum_{n=1}^N \Omega_n |n\rangle\langle n| + \sum_{m \neq n} J_{m,n} |m\rangle\langle n| \quad \hat{H}_v = \sum_{n=1}^N \sum_{q=1}^Q \omega_q \hat{a}_{n,q}^\dagger \hat{a}_{n,q}$$

$$\hat{H}_{ev} = \sum_{n=1}^N \sum_{q=1}^Q \omega_q \sqrt{s_q} |n\rangle\langle n| (\hat{a}_{n,q} + \hat{a}_{n,q}^\dagger)$$

